

PHOTOMOD 6.3

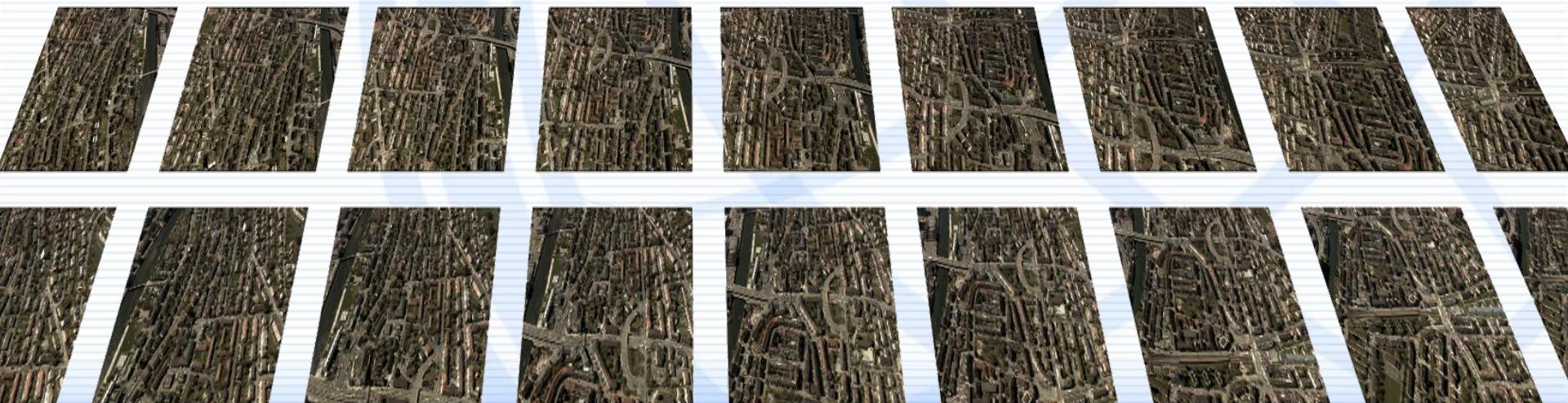
new features

Dmitry Kochergin
Head of Technical support department
Racurs, Russia

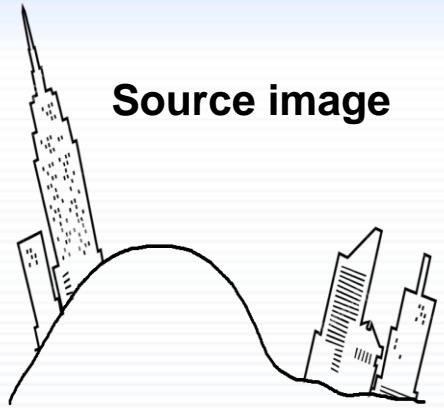
Hadera. Israel. October 2017

PHOTOMOD 6.3 highlights

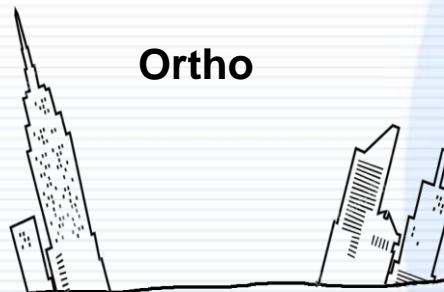
- ✓ Fully automatic generation of True-Ortho
- ✓ Improved dense DSM quality
- ✓ Point cloud filtering capabilities
- ✓ New pan-sharpening method (EPCA)
- ✓ Additional stereovectorization tools
- ✓ Increased reliability of UAS aerial triangulation
- ✓ Accelerated orthorectification for urban and mountain area
- ✓ New report of UAS-project processing
- ✓ Export of RPC
- ✓ PHOTOMOD UAS interface changes
- ✓ UltraCam metadata import improvements



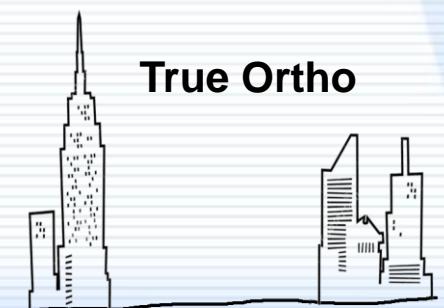
True Ortho



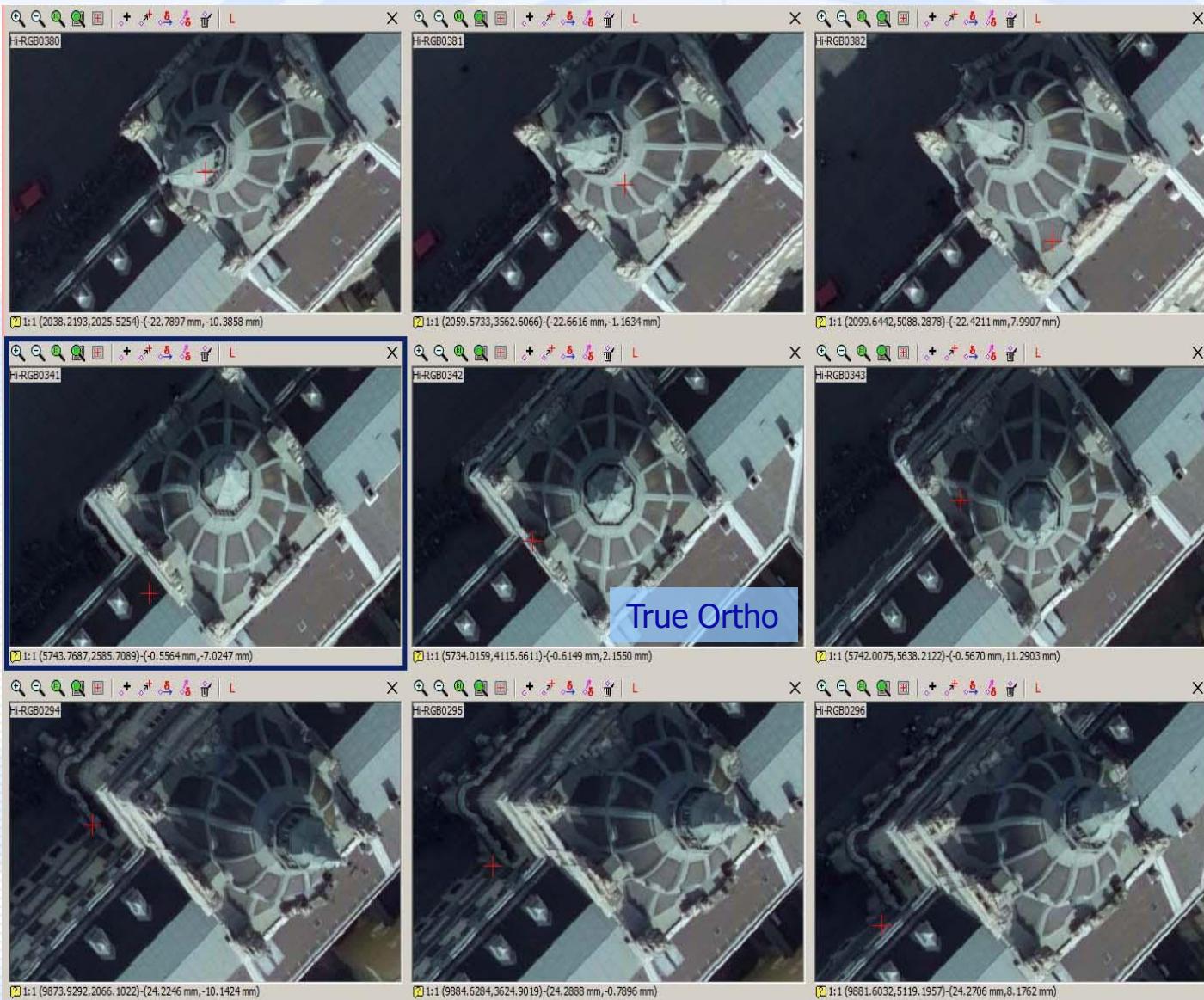
Source image



Ortho



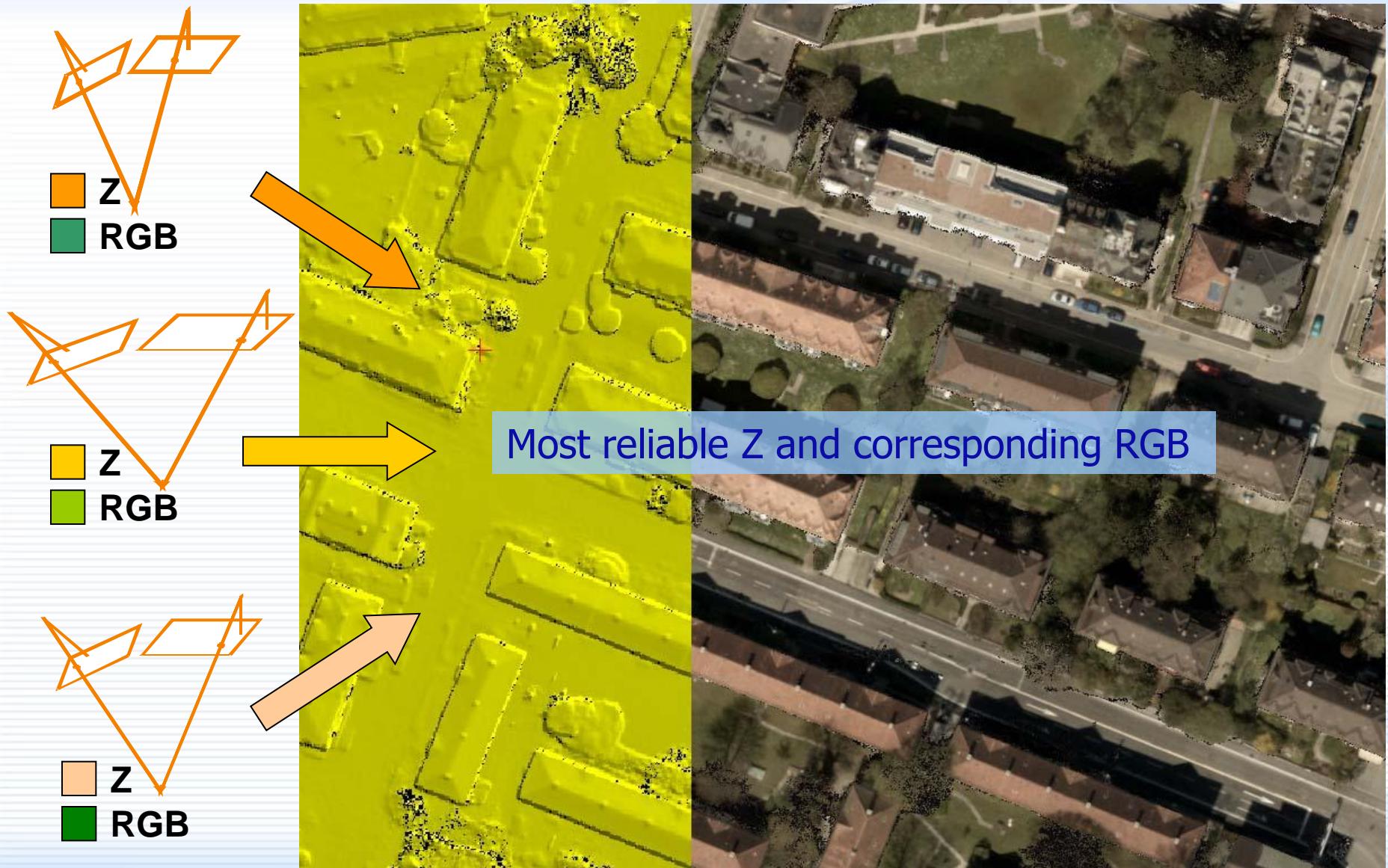
True Ortho



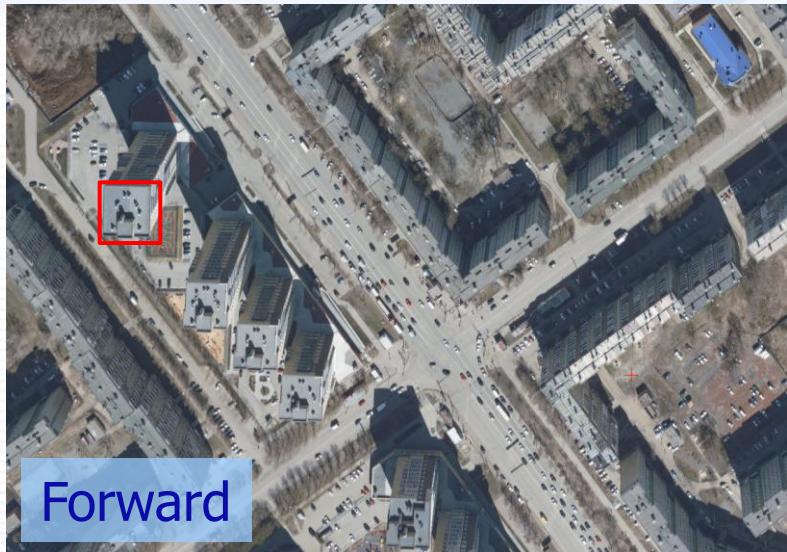
True-Ortho in PHOTOMOD



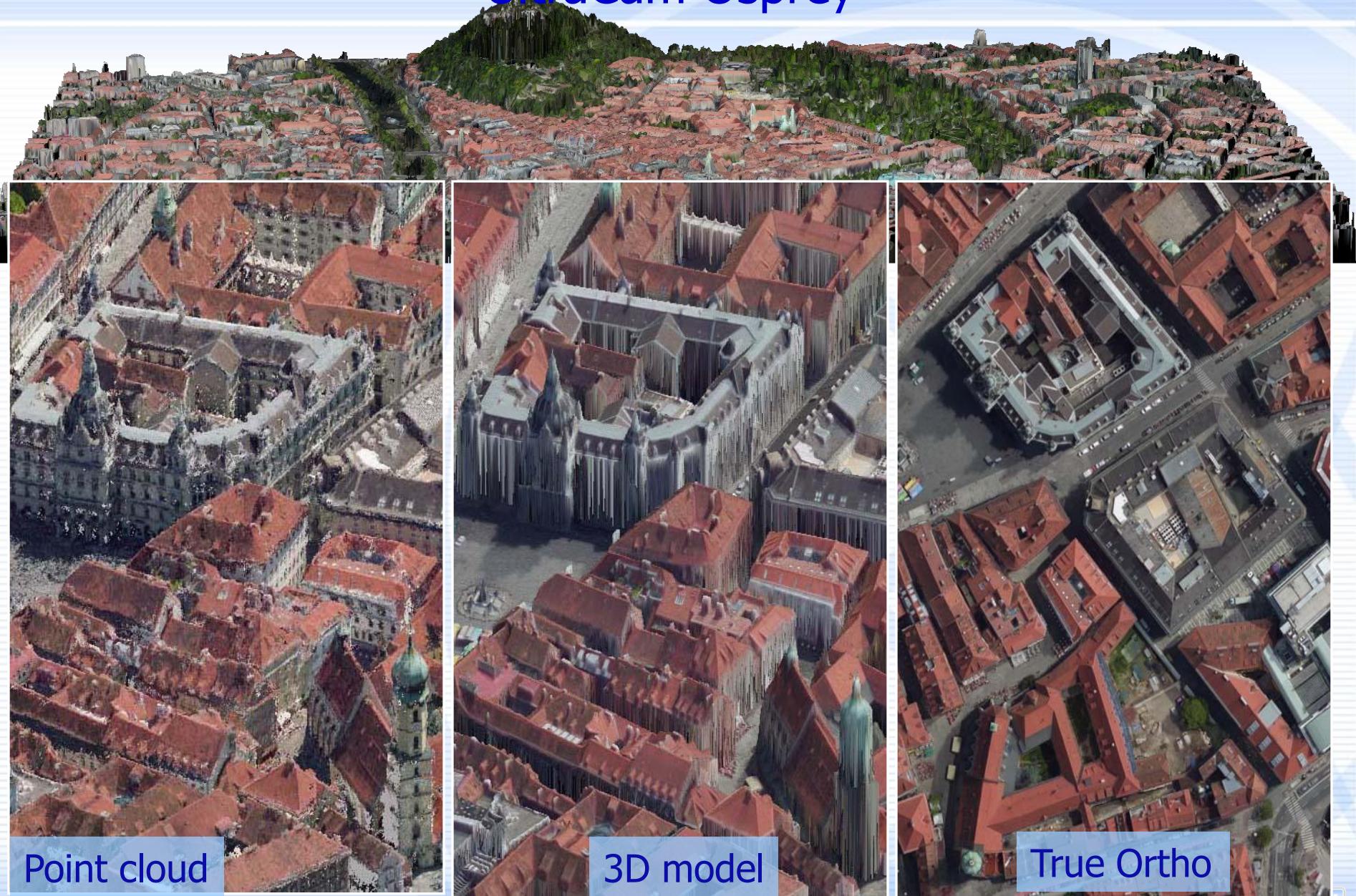
True Ortho pixel value (RGB)



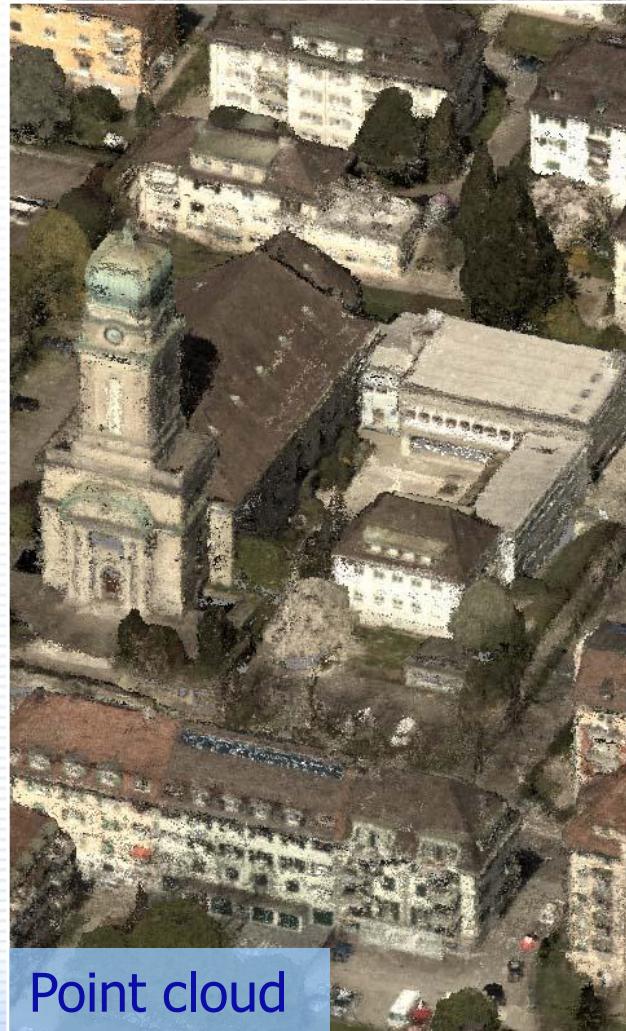
True Ortho (Leica RCD-30 Oblique)



UltraCam Osprey



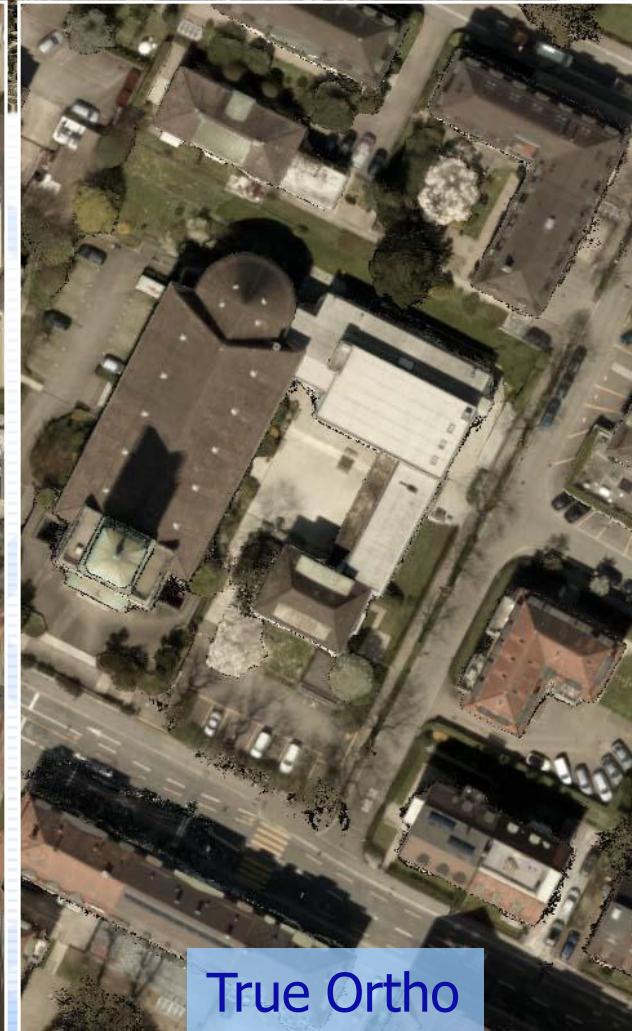
Leica RCD-30 Oblique



Point cloud

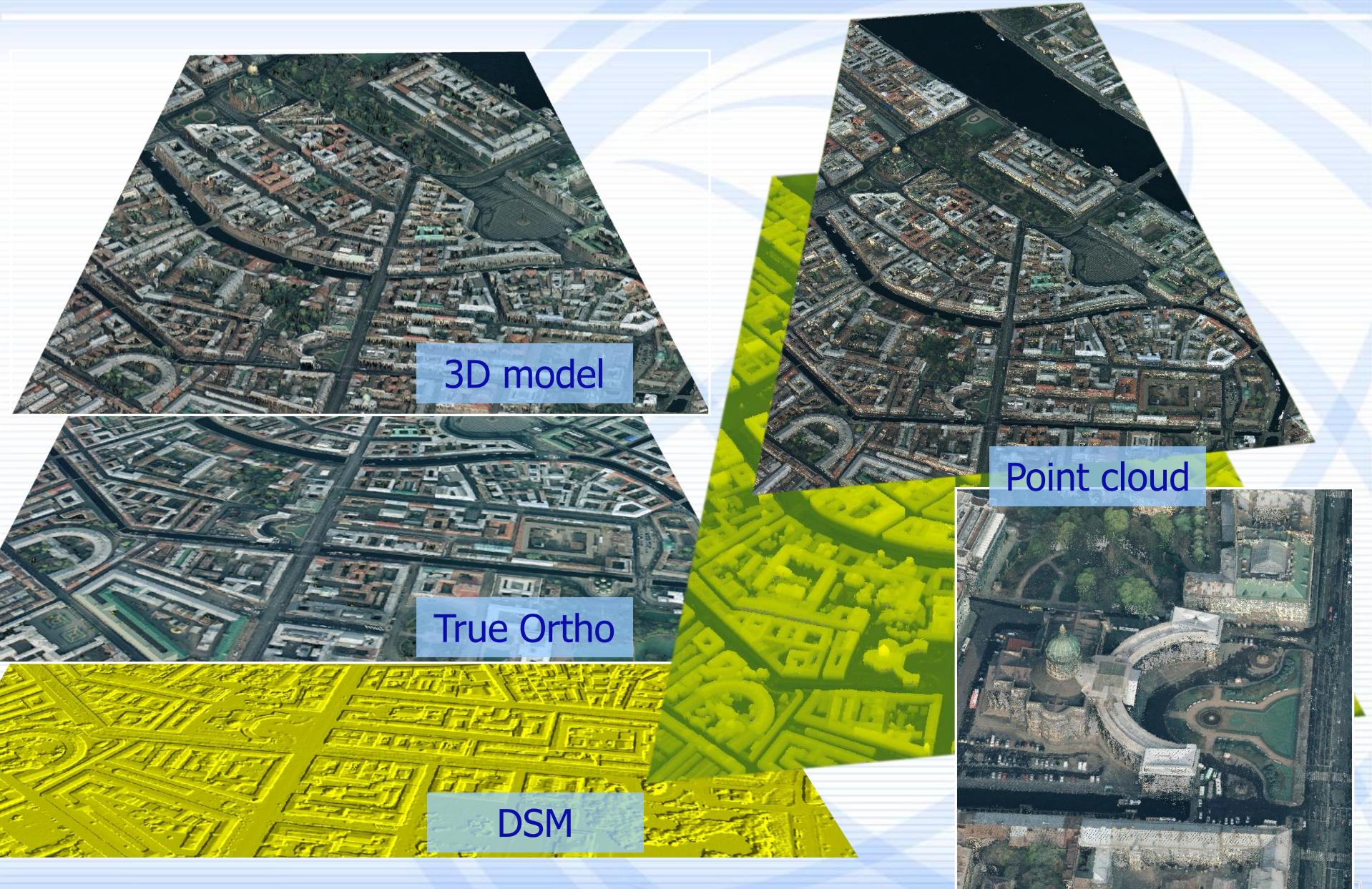


3D model

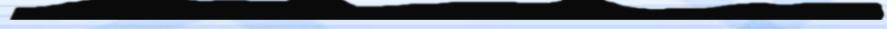
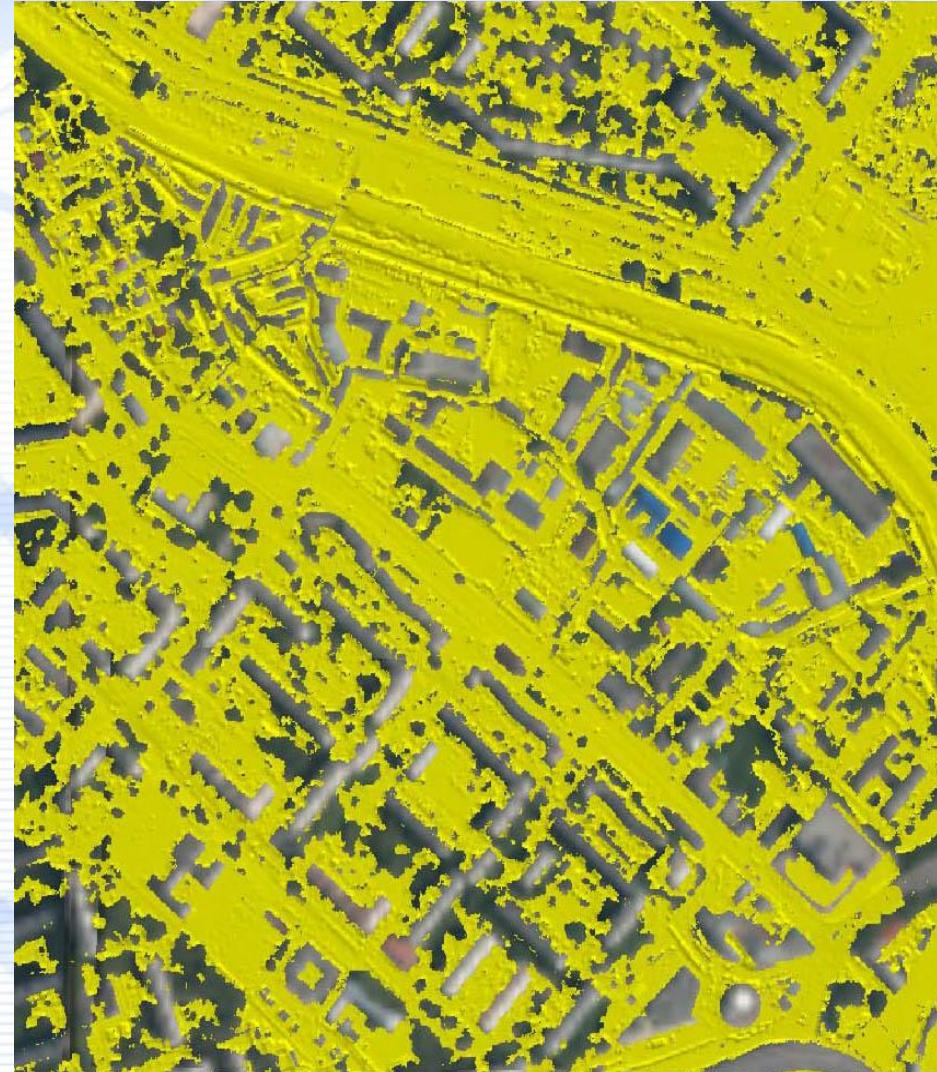
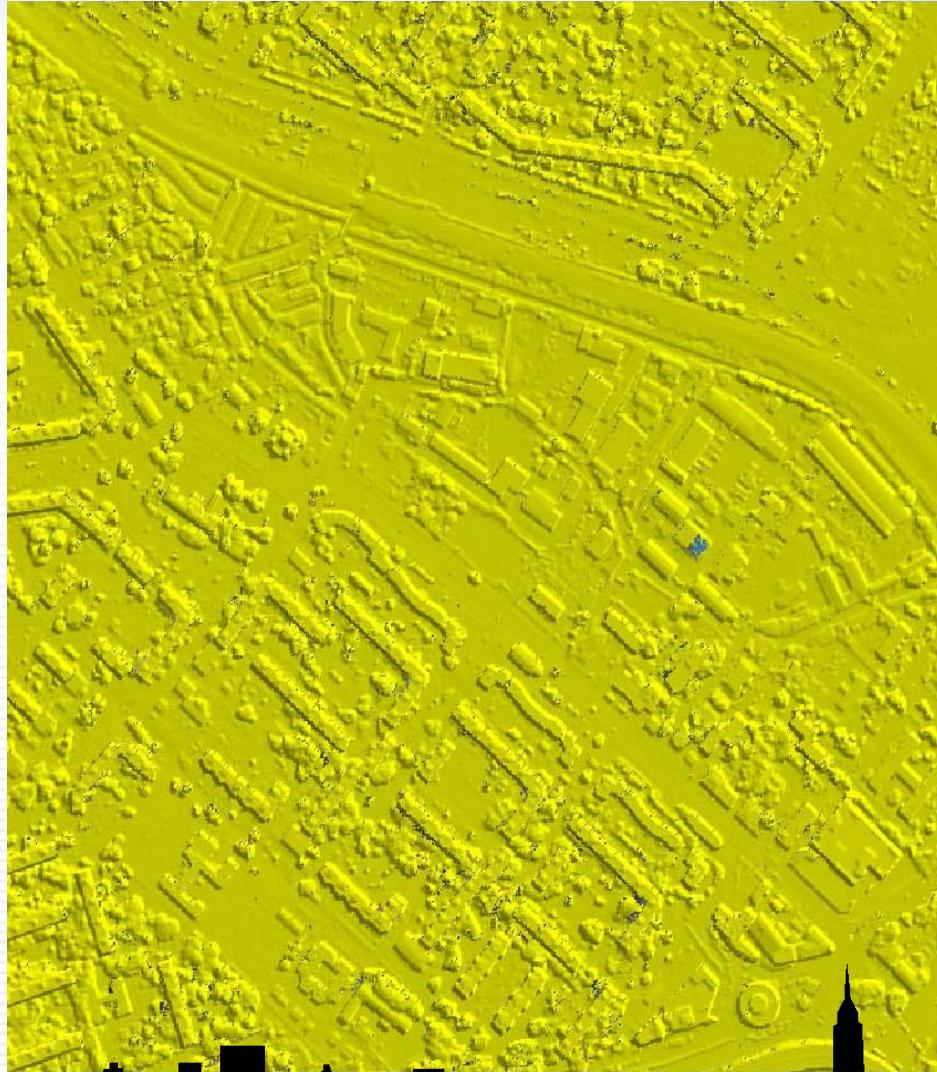


True Ortho

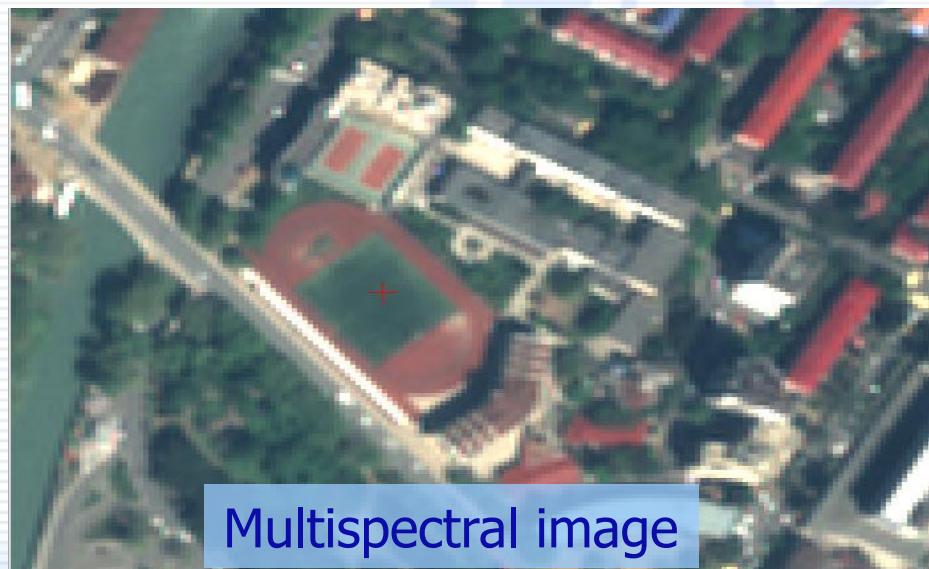
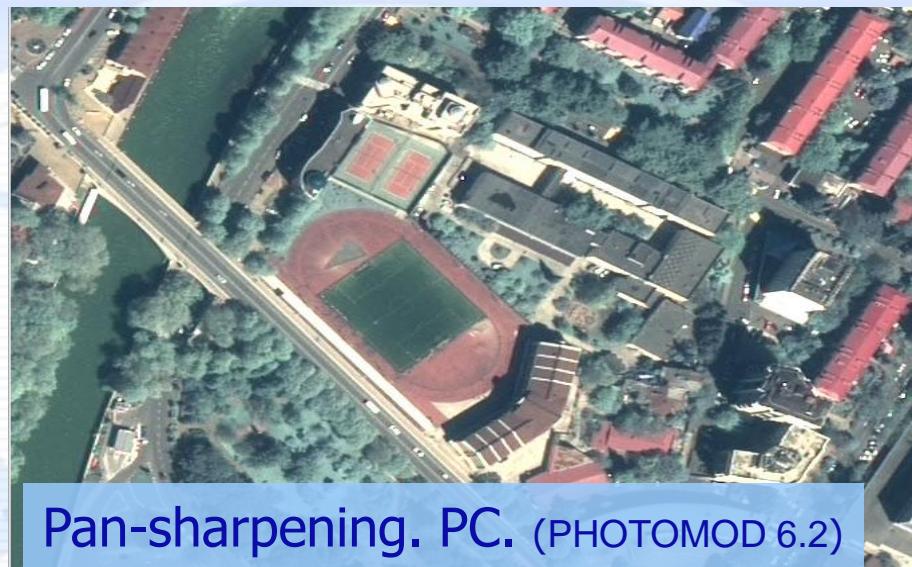
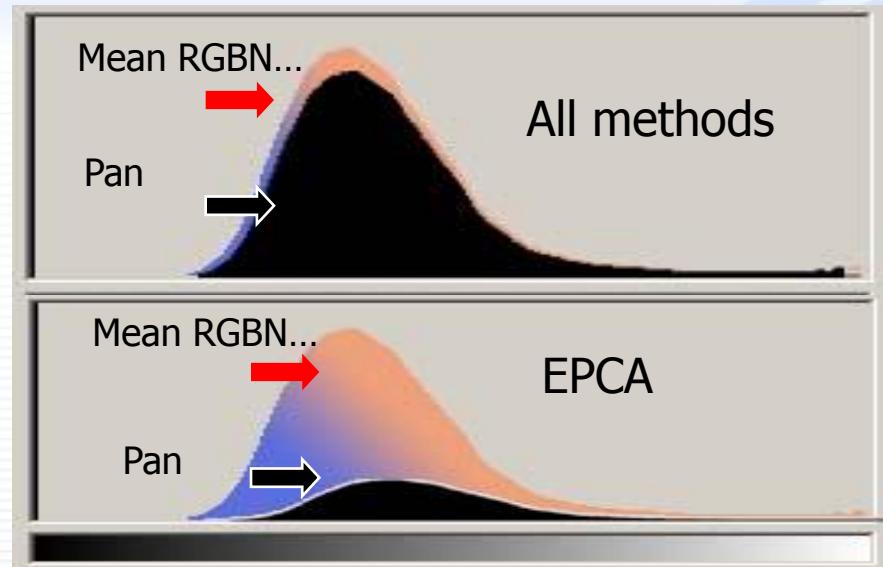
3D model vs Point cloud



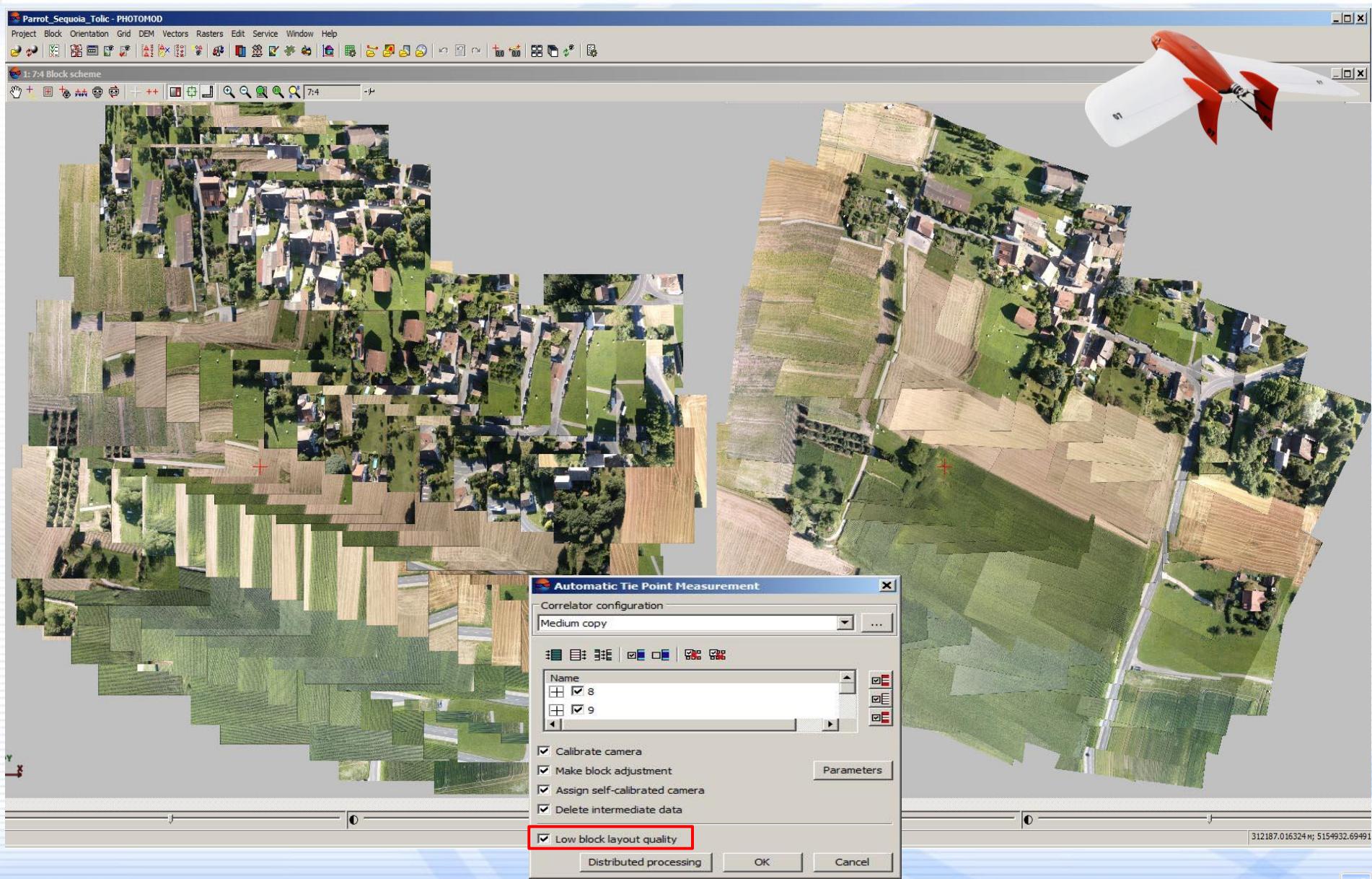
Filtering by slope angle (DSM - DTM)



EPCA. New Pan-sharpening method



PHOTOMOD UAS. Low quality of block layout



PHOTOMOD UAS. Interface changes

PHOTOMOD 6.2

The interface shows a top navigation bar with Project, Block, Orientation, Grid, DEM, Vectors, Rasters, Service, Window, Help. Below it is a toolbar with Triangulation, Compute DEM, Compute Orthophoto, and various icons. A main panel displays a workflow:

1. Add images
2. Interior orientation
3. Exterior orientation
4. GCP (highlighted with a red box)
5. Relative orientation
6. Adjustment

Sub-options for each step include Import catalog, Import measurements, Automeasure tie point, Import tie points, Block adjustment, and Direct georeferencing.

PHOTOMOD 6.3

The interface is similar to 6.2 but includes a red box highlighting the "Relative orientation" step. The main panel now includes a "Tie points list" option under step 4. The "GCP" step is also highlighted with a red box.

Below the main panel, there is a large data grid containing numerous numerical values, likely representing survey or photogrammetric data.

PHOTOMOD UAS. Processing report

Polygon_test_Ptero_SGM_DIMA_test_new_fb - PHOTOMOD

Project Block Orientation Grid Terrain Vectors Rasters Edit Service Window Help

Report

Report type:

Correlator configuration	---
Calibrate camera	On
Make an adjustment	On
Apriori accuracy of measurements on images, pix	1.000
Assign the camera after calibration	On
Delete temporary data	On

Adjustment parameters:

Initial approximation method:	By block scheme
Adjustment method:	Bundle adjustment
Systematic error compensation	For block
Calibration type:	Physical
Time of processing	---

Processing results

Results of camera calibration

	Initial data	Optimized data
Camera	NikonD800[dist_avg][tripl_avg] [selfcal] 2.x-cam	NikonD800[dist_avg][tripl_avg] [selfcal] 2.x-cam
Focal length, mm	52.136	52.136
Principal point (X/Y), mm	-0.048 / 0.148	-0.048 / 0.148
Pixel size, mm	0.005	0.005
Type of distortion	Formula	Formula
Point of symmetry (X/Y), mm	-0.048 / 0.148	-0.048 / 0.148

Ground control and check points accuracy

Ground control point residuals

N	Apriori X/Y/Z accuracy	Ex. метр	Ey. метр	Ez. метр	Exy. метр
OP05	0.020000/0.020000/0.050000	0.073102	0.076732	0.109174	0.105980
OP13	0.020000/0.020000/0.050000	0.000389	0.111450	0.047207	0.111451
OP14	0.020000/0.020000/0.050000	0.011480	0.054531	0.000151	0.055726
OP47	0.020000/0.020000/0.050000	0.005572	0.035510	0.048554	0.035945

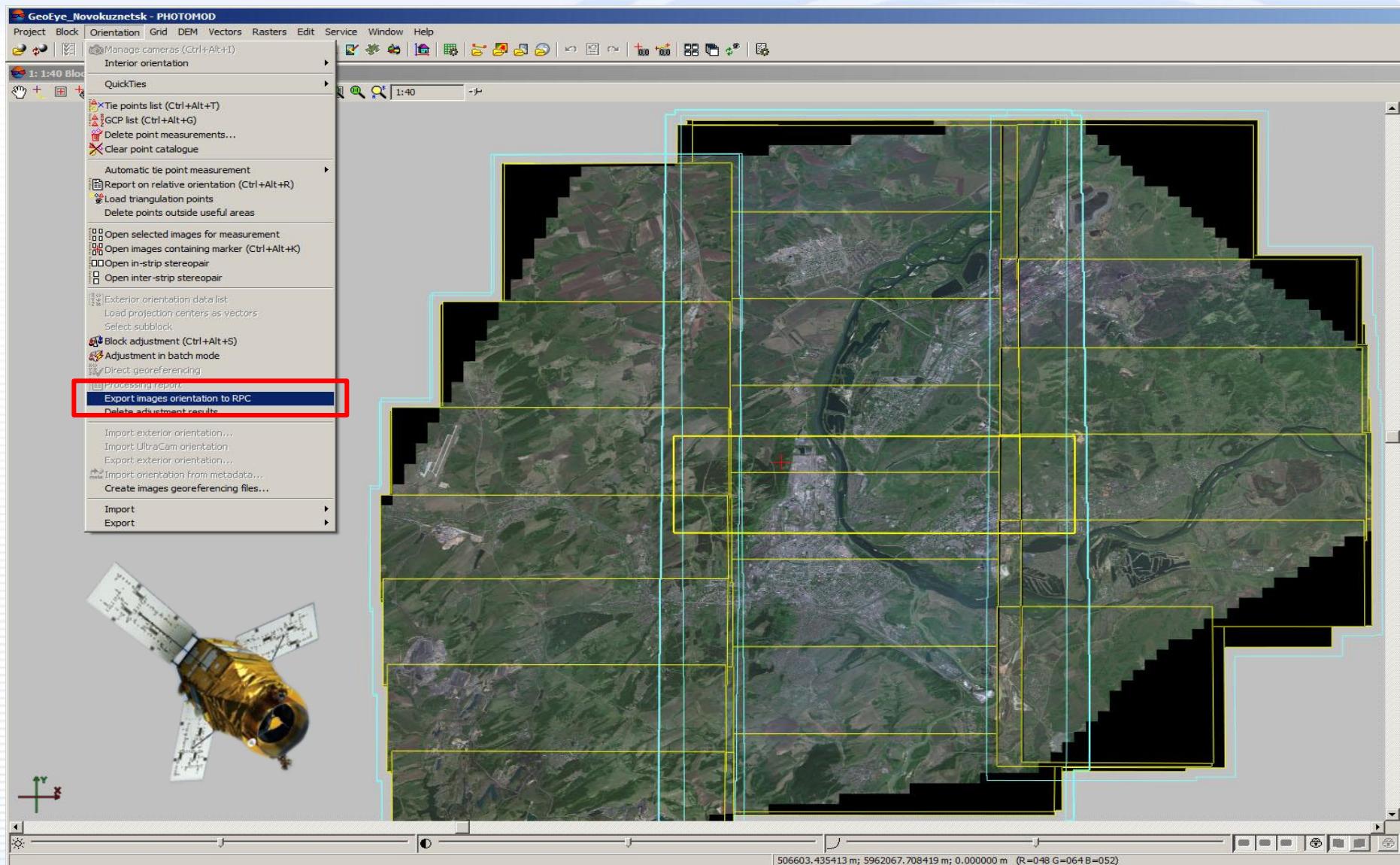
Close

349 м; 6077759.525645 м; 0.000000 м (R=192 G=192 B=192)

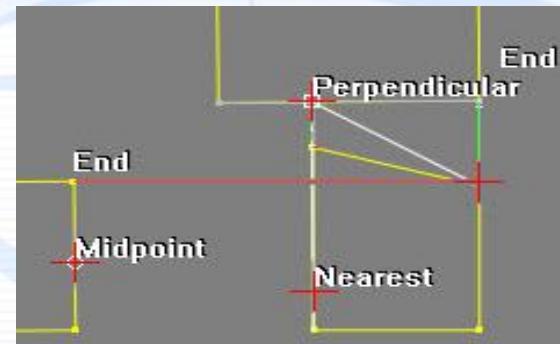
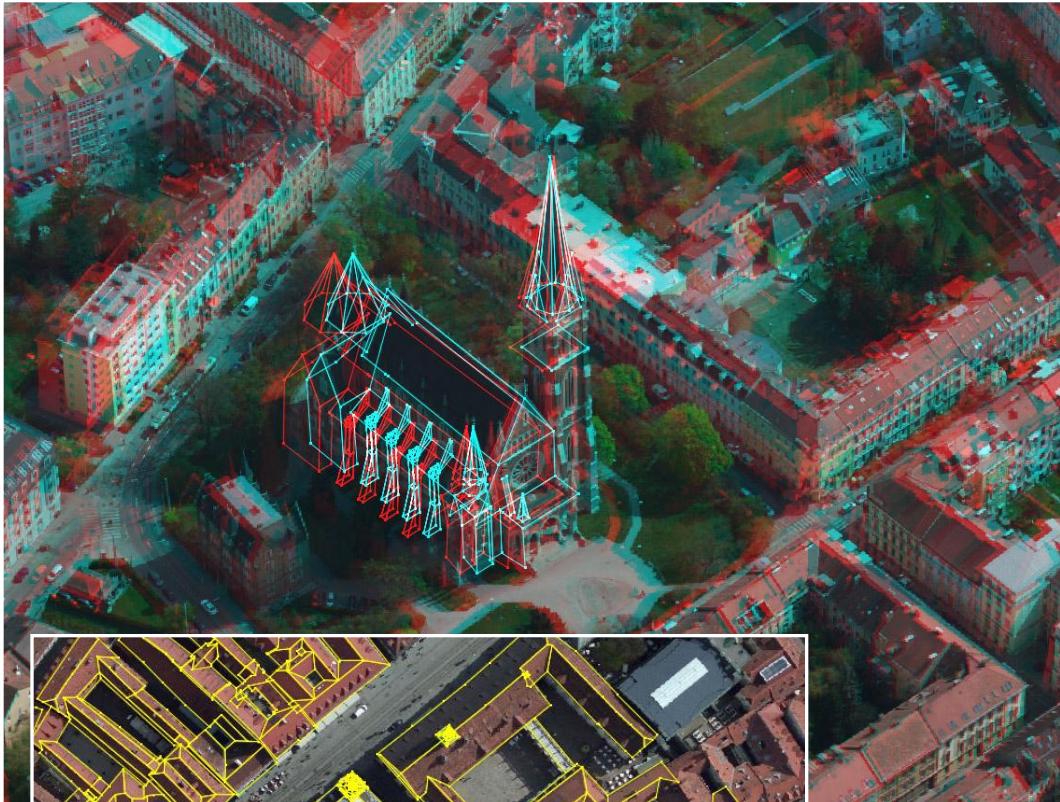
WGS 84 /UTM 37N



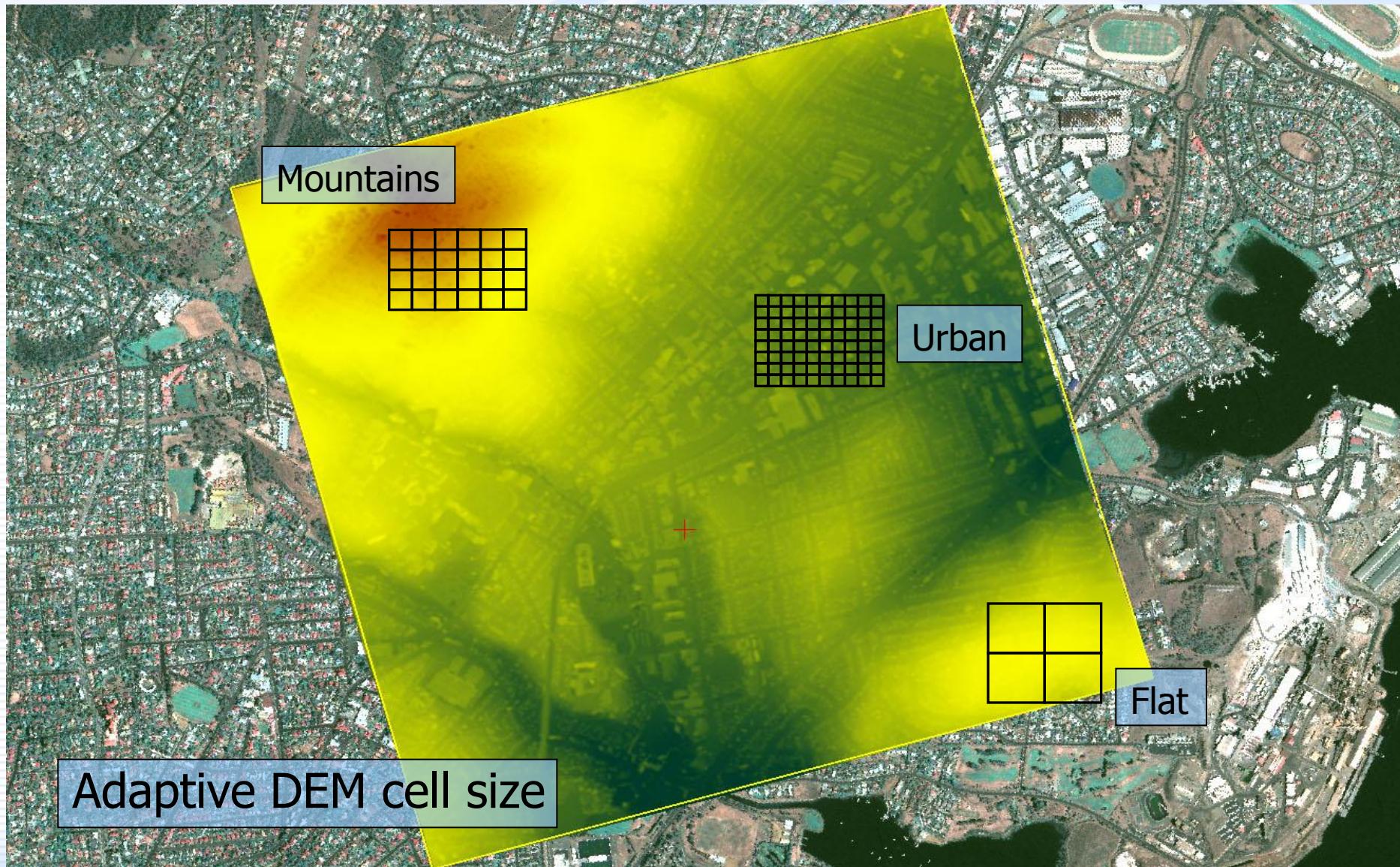
Export of RPC coefficients



New snapping and 3D-vectorization tools



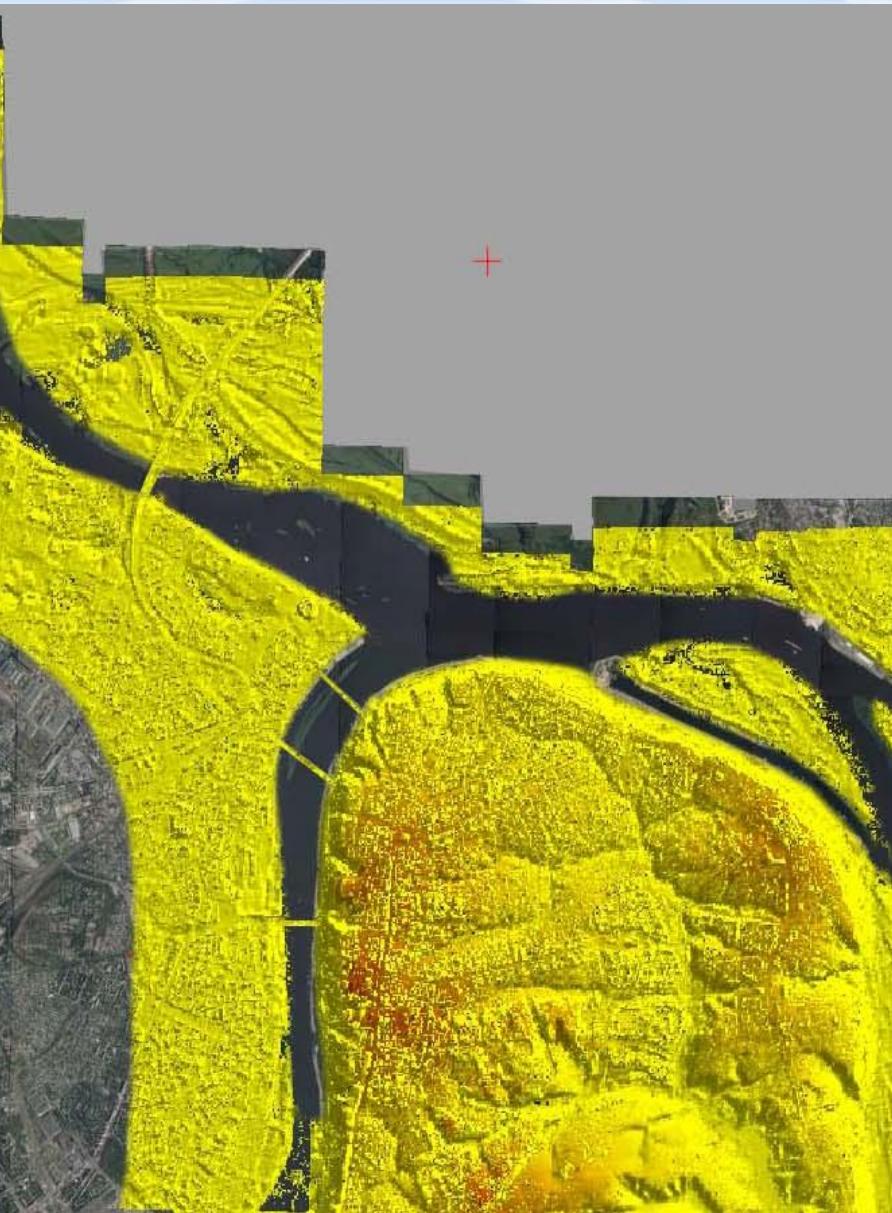
Accelerated orthorectification for urban and mountain area



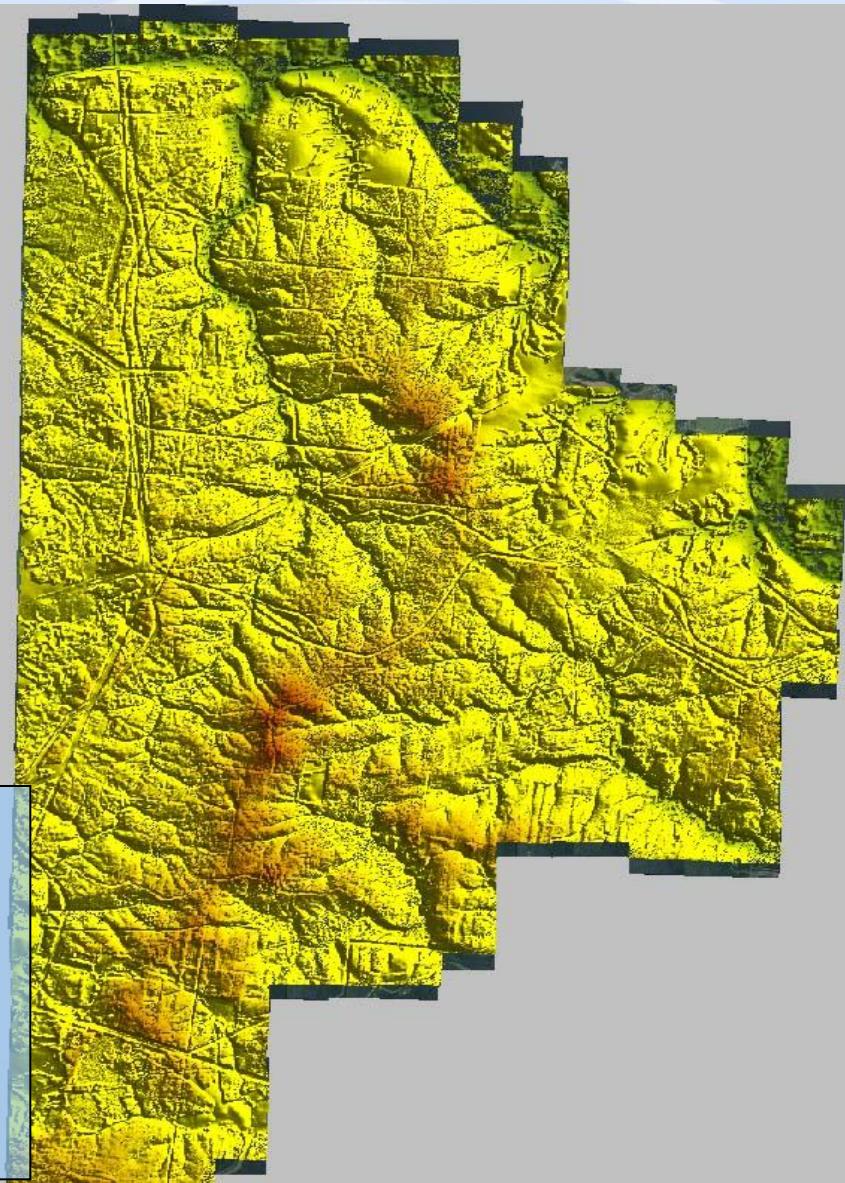
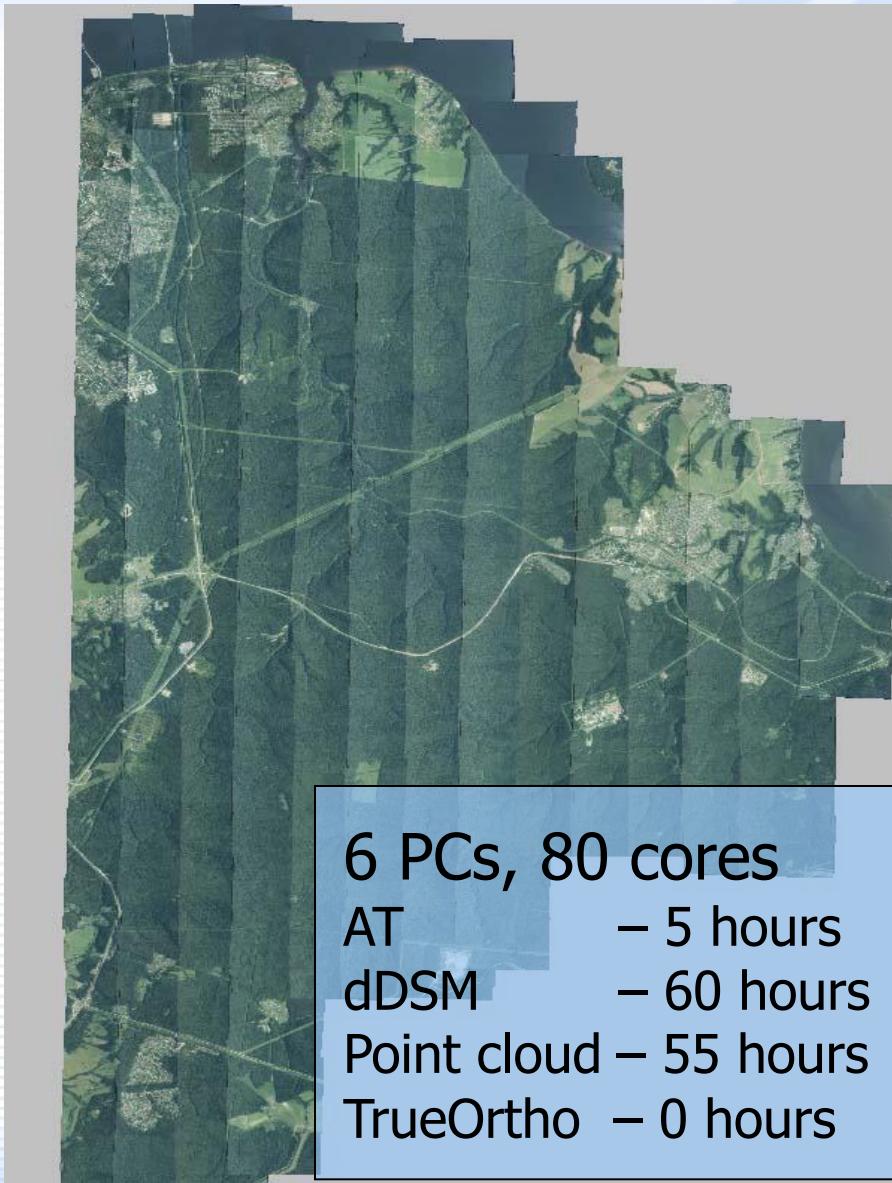
Productivity. AT + dDSM(SGM) + Point cloud + True Ortho



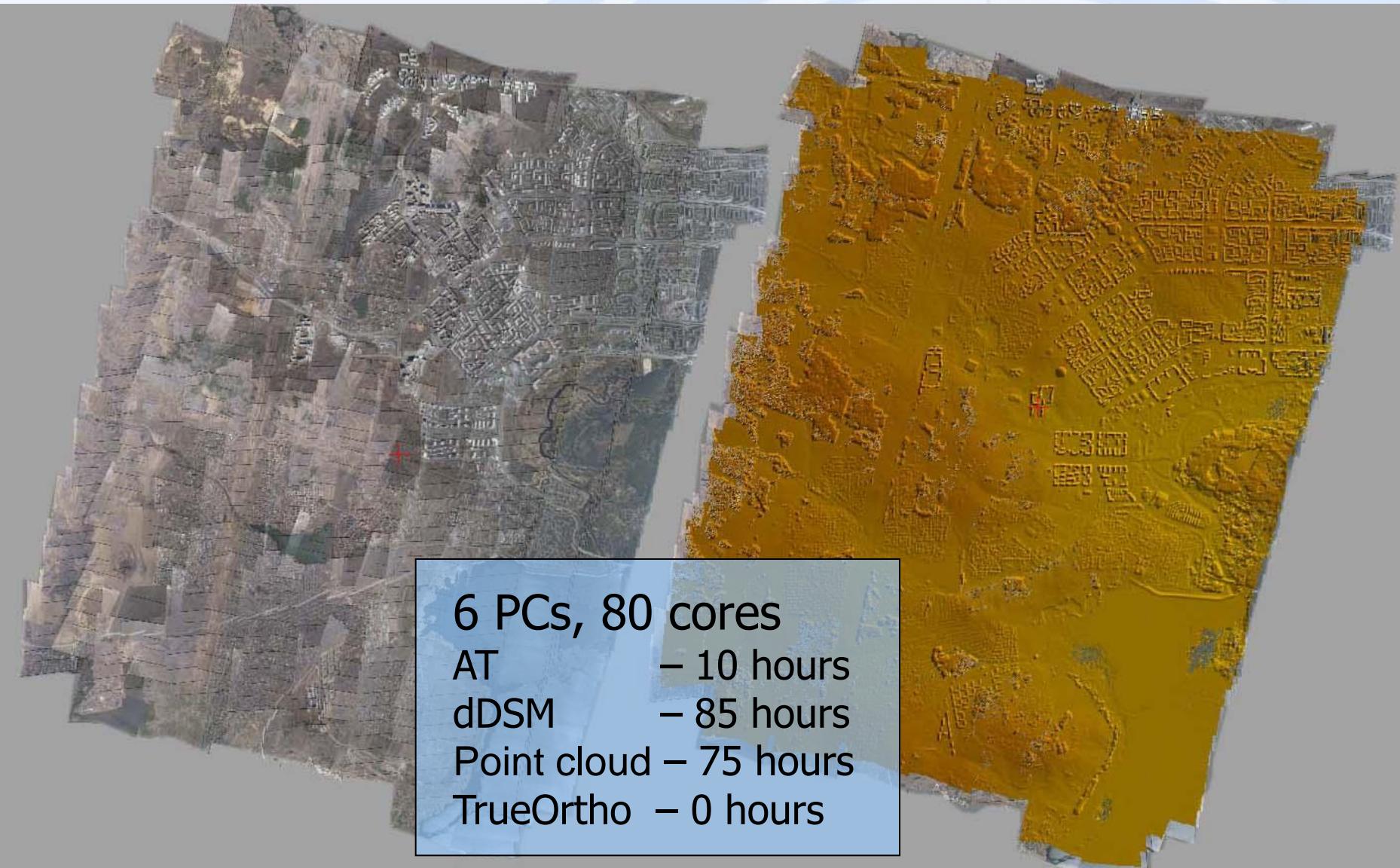
UltraCam Eagle, 922 images (13080 x 20010 pix), H=2000m, GSD=0.1m



6 PCs, 80 cores
AT – 6 hours
dDSM – 75 hours
Point cloud – 70 hours
TrueOrtho – 0 hours



6 PCs, 80 cores
AT – 5 hours
dDSM – 60 hours
Point cloud – 55 hours
TrueOrtho – 0 hours



Utility for productivity estimation

 Calc Performance PHOTOMOD

Camera Advanced Exit

Active Camera: UltraCamEagle >

Survey

Instrip overlap, %	80
Interstrip overlap, %	60
Images in strip	50
Number of strips	30
Number of Images	1500
<input checked="" type="radio"/> GSD, m	0.1
<input type="radio"/> Height above ground, m	1538.46
Area of survey, km ²	342.972

Hardware

Write speed, MB/s	32
Number of cores	12
Image size, MB	261.7

SGM

Cell size, m	0.3
Performance for block Mpix / 1 core / h	39.10
Performance for stereopair Mpix / 1 core / h	121.51

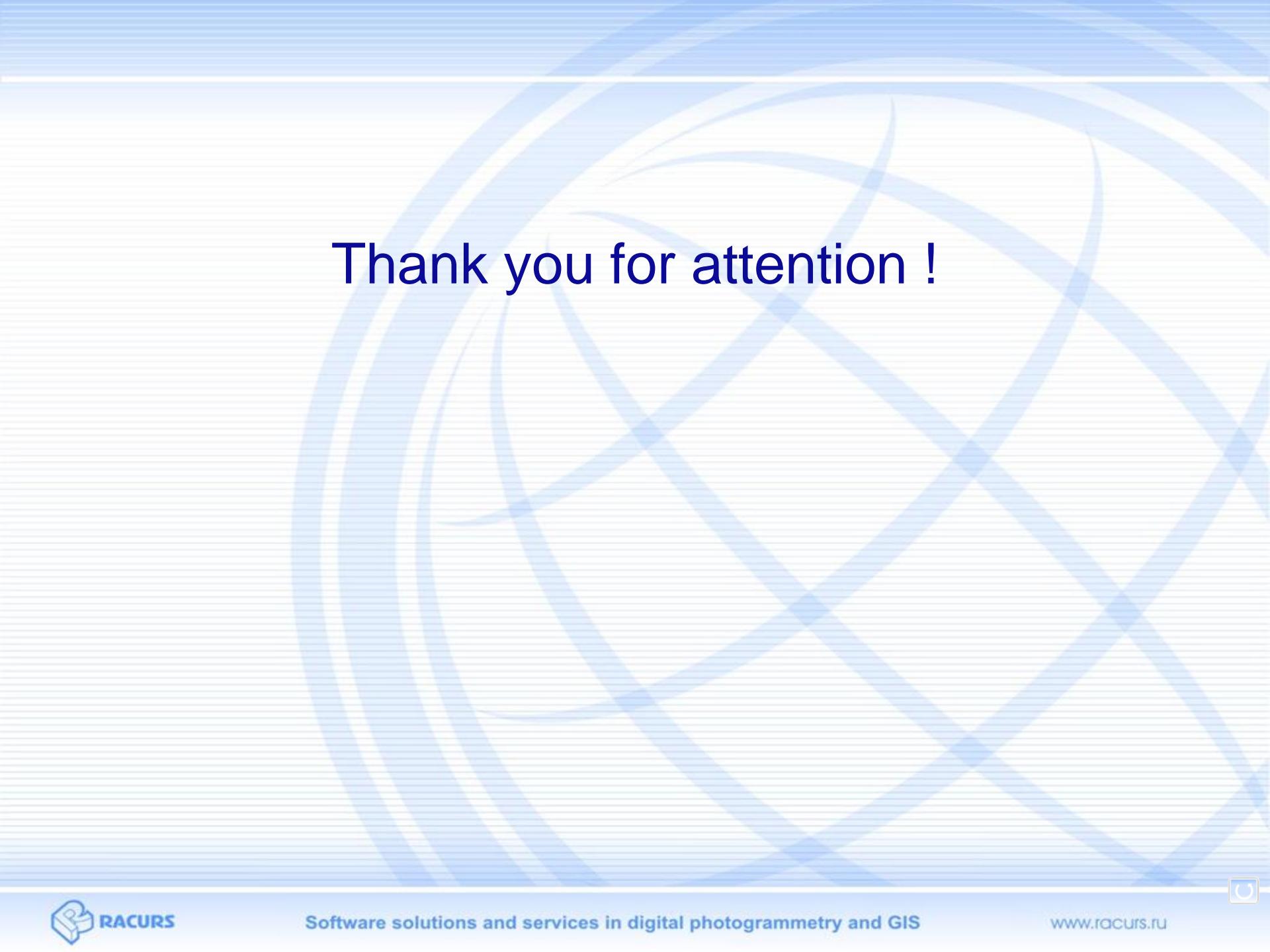
Time

Images loading, h	3.41
AT, h	0.68
SGM, h	24.37
Total, h	28.46

(c) Racurs 2016

Welcome to the master-class (Wednesday)





Thank you for attention !

